

# *Measurement of Global Instability of Compact Torus by use of 3-D Tomography*



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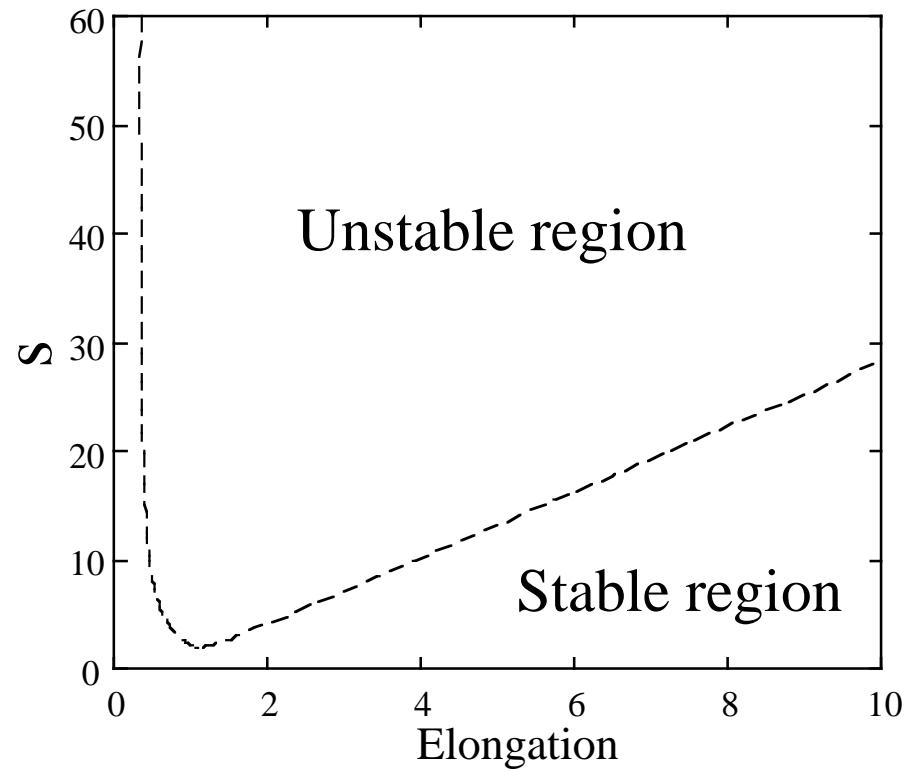
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*need to investigate stability region of tilt mode in a wide range of S-E*

- ◆ Elongation E and s-value determine the stable region.

E : ratio of separatrix length to separatrix diameter

s : ratio of separatrix radius to ion gyro-radius

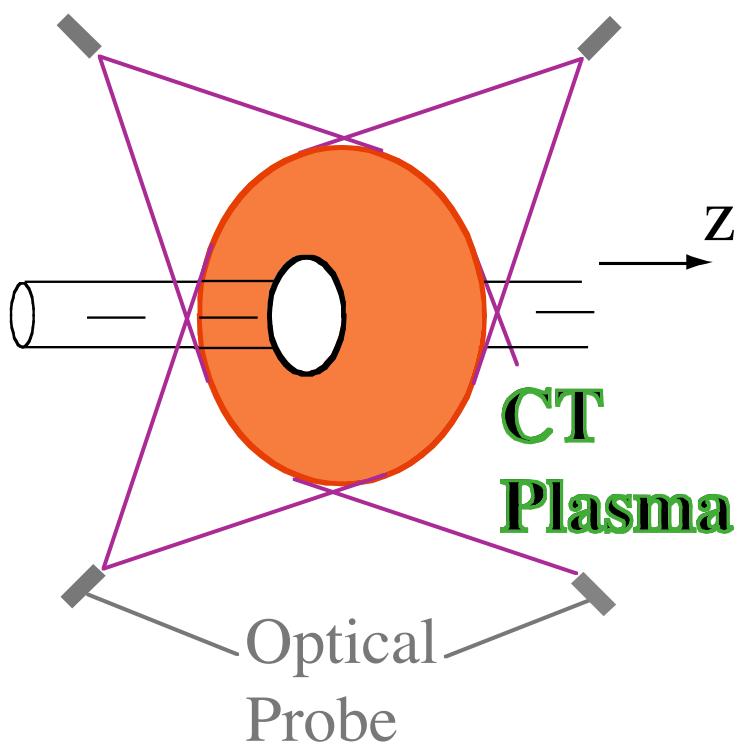


H. Ji, et al., Phys. Plasmas **5** No. 10 3685 (1998).

# *What is the 3-D tomography?*



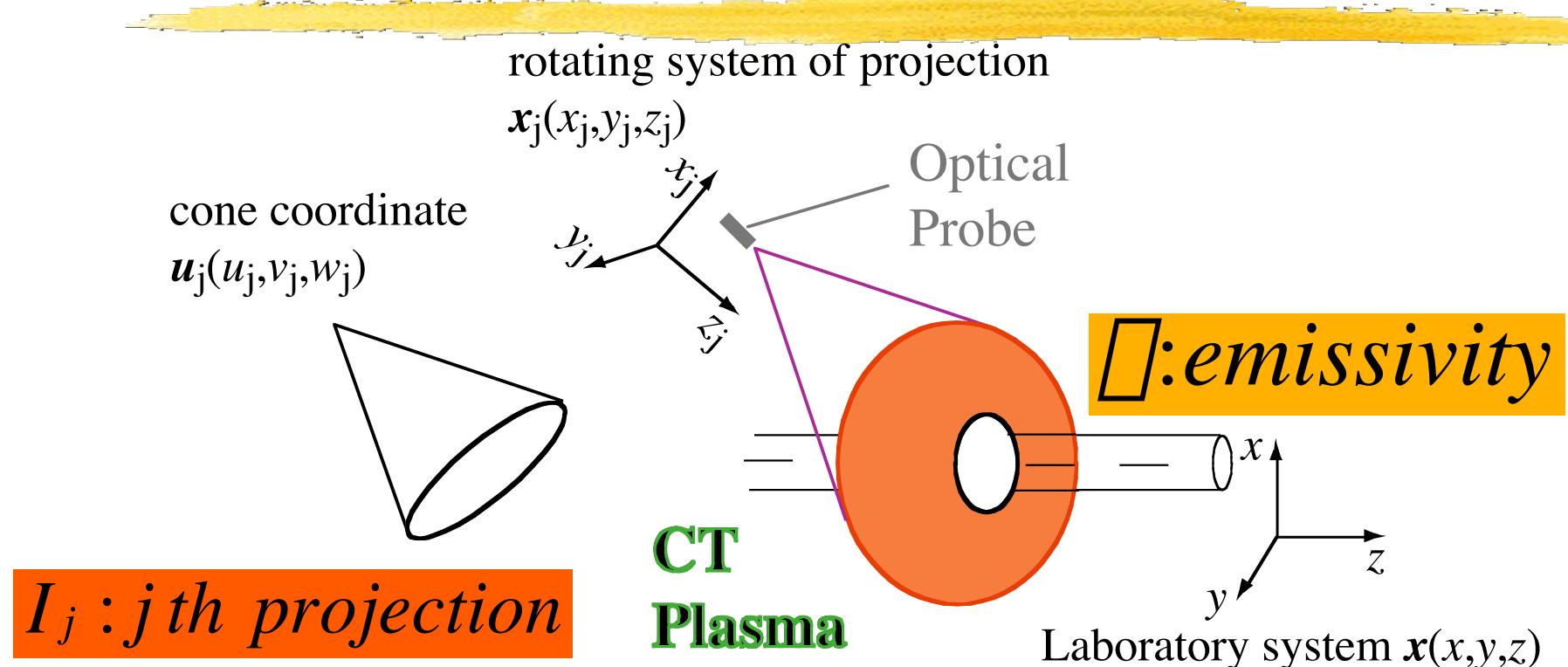
#N projections



- 3-D emissivity profiles of CTs are directly reconstructed using a number of 2-D projections.
- Our reconstruction error calculation suggests that the most effective number of projection is 16.
- Its reconstruction algorithm is based on the maximum entropy principle.

# *Principle of 3-D tomography*

## Transformation of coordinate (1/2)



$$X_j = R_j X$$

$$R_j(\square, \square) = \begin{bmatrix} \cos \square \cos \square & \cos \square \sin \square & \square \sin \square \\ \square \sin \square & \cos \square & 0 \\ \square \sin \square \cos \square & \sin \square \sin \square & \cos \square \end{bmatrix}$$

## Transformation of coordinate (2/2)

$$u_j = \frac{x_j}{1 + z_j/d_j}, \quad x_j = u_j(1 + w_j/d_j)$$

$$v_j = \frac{y_j}{1 + z_j/d_j}, \quad y_j = v_j(1 + w_j/d_j)$$

$$w_j = z_j, \quad z_j = w_j.$$

projection  $I_j$ , emissivity  $\square$

$$I_j(u, v) = \iint_{\mathbb{R}^2} dX \square(x) \square(u \square U_j(x)) \square(v \square V_j(x))$$

$$= \iint d\omega \left| \frac{\partial(x, y, z)}{\partial(u, v, w)} \right| \square(x, y, z)$$

$$\frac{\partial(x, y, z)}{\partial(u, v, w)} = (1 + w_j/d_j)^2$$

# Using Maximum Entropy Method (MEM) (1/2)

Entropy functional : an index of smoothness of an image

$$\mathcal{H}(\mathbf{f}) = \mathbb{E} \int_D dw \mathbf{f}(\mathbf{x}) \ln(\mathbf{f}(\mathbf{x})V)$$

$V$  : normalization constant

Maximize

Lagrange functional      with  $\tilde{I}_j = const.$

$$L(\mathbf{f}, \lambda) = \mathcal{H}(\mathbf{f}) - \lambda \int_{j=1}^J du dv \mathbf{f}_j(u, v) \tilde{I}_j(u, v)$$

$\lambda$  : Lagrange multiplier

$J$  : number of projections

$$\tilde{I}_j(u, v) \equiv I_j(u, v) \int dw |J| \mathbf{f}(x_j, y_j, z_j)$$

# Using Maximum Entropy Method (MEM) (2/2)

From  $\square L = 0$

$$\square(\mathbf{x}) = \frac{1}{V} \prod_{l=1}^J H_l(U_j(\mathbf{x}), V_j(\mathbf{x}))$$

Calculating  $H_l(U_j(\mathbf{x}), V_j(\mathbf{x}))$

results in determination of  $\square(\mathbf{x})$

$$I_j(u, v) = \frac{1}{V} \prod_{l \neq j} dw |J| \prod_{l=1}^J H_l(U_j, V_j)$$

$$I_j(u, v) = \frac{1}{V} H(u, v) \prod_{l \neq j} dw |J| \prod_{l=1}^J H_l(U_{lj}, V_{lj})$$

$H_j$  are obtained by iteration of the calculation



Experimental data

$$H_j^{i+1}(u, v) = \frac{I_j(u, v)V}{\sum_{l=1}^J dw |1 + w/d_j|^2 H_l(U_{lj}, V_{lj})}$$

for  $j = i \pmod J + 1$ :

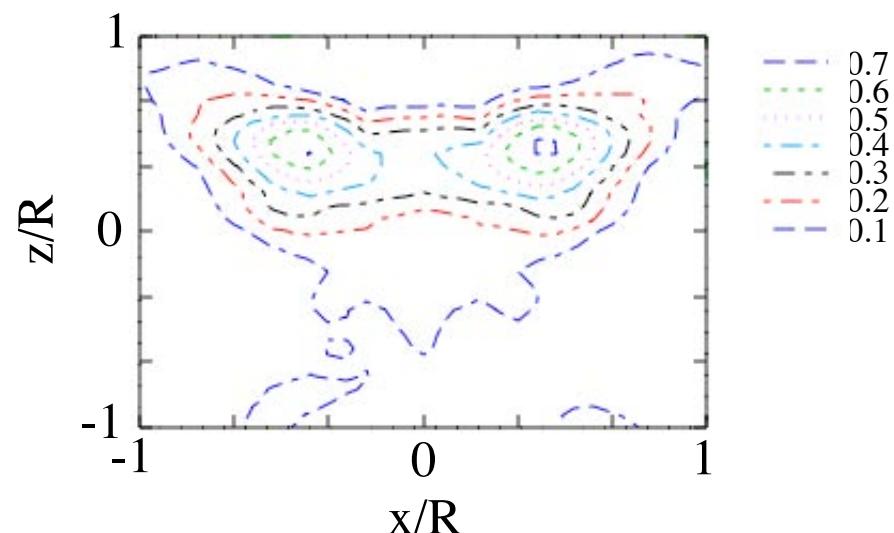
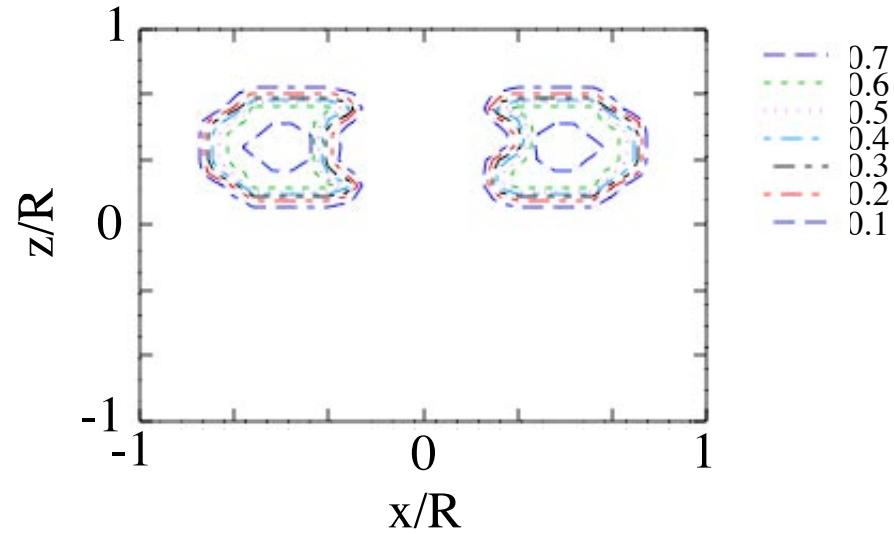
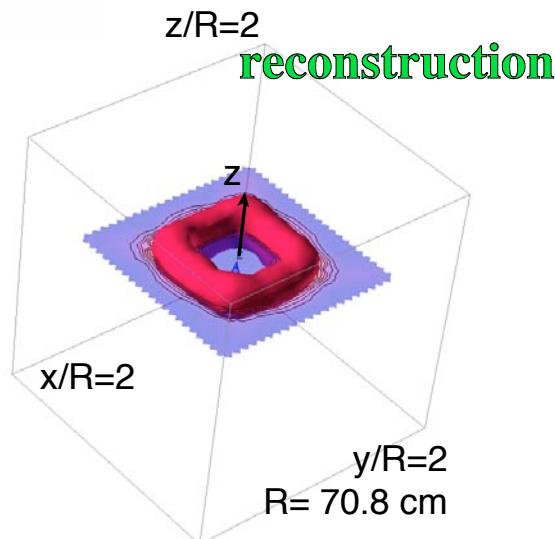
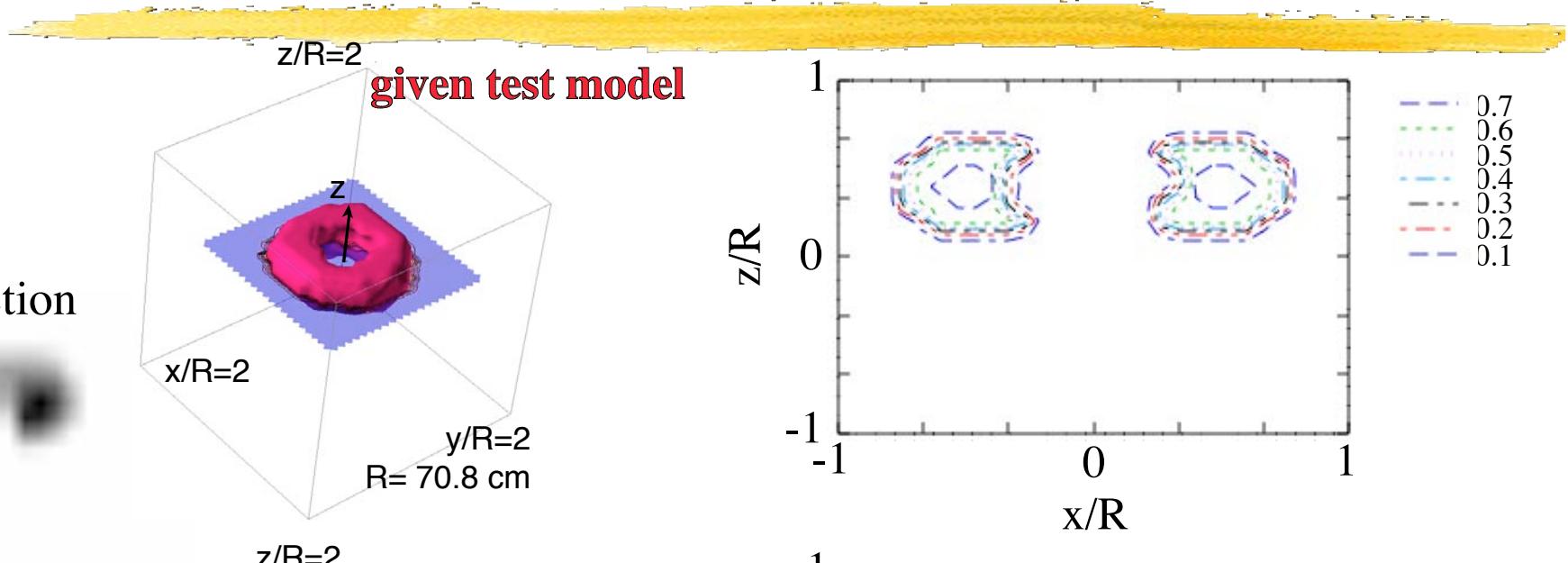
$$H_j^{i+1}(u, v) = H_j^i(u, v) \quad \text{for } j \neq i \pmod J + 1:$$

$$H_j^0(u, v) = \begin{cases} 1, & \text{if } I_j(u, v) \neq 0 \\ 0, & \text{if } I_j(u, v) = 0 \end{cases}$$

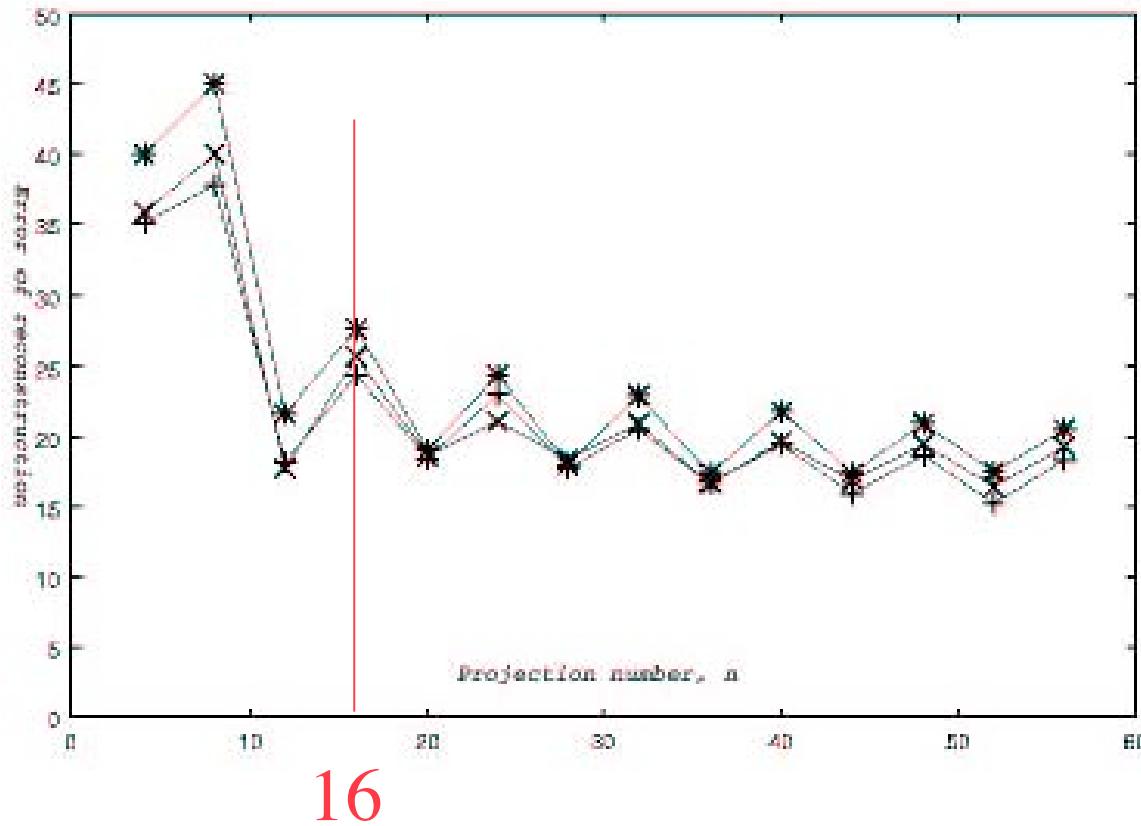
Initial value

# *Calculation of a test model*

ch.7  
projection

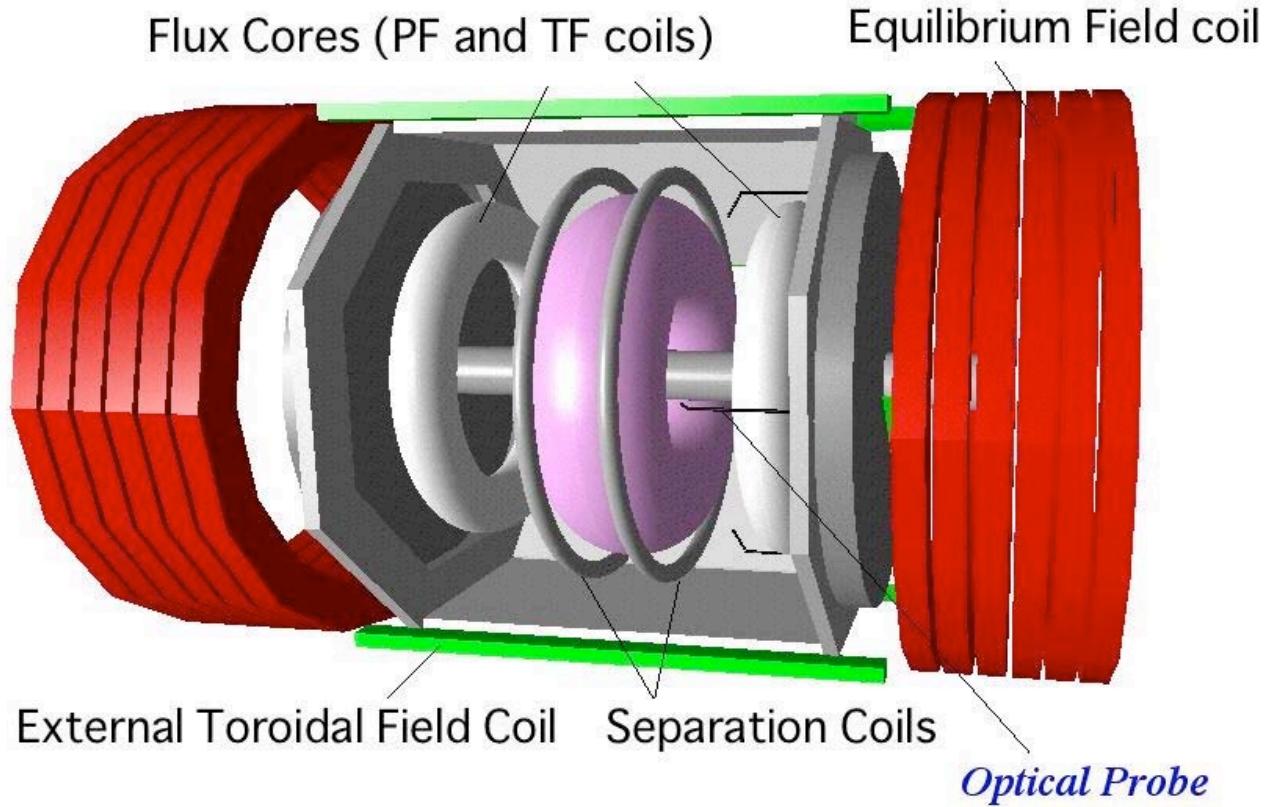


*The minimum number of projection is 16 based on our model calculation.*



Reconstruction error as a function of projection number  
for toroidal mode  $n=1$  to  $n=3$

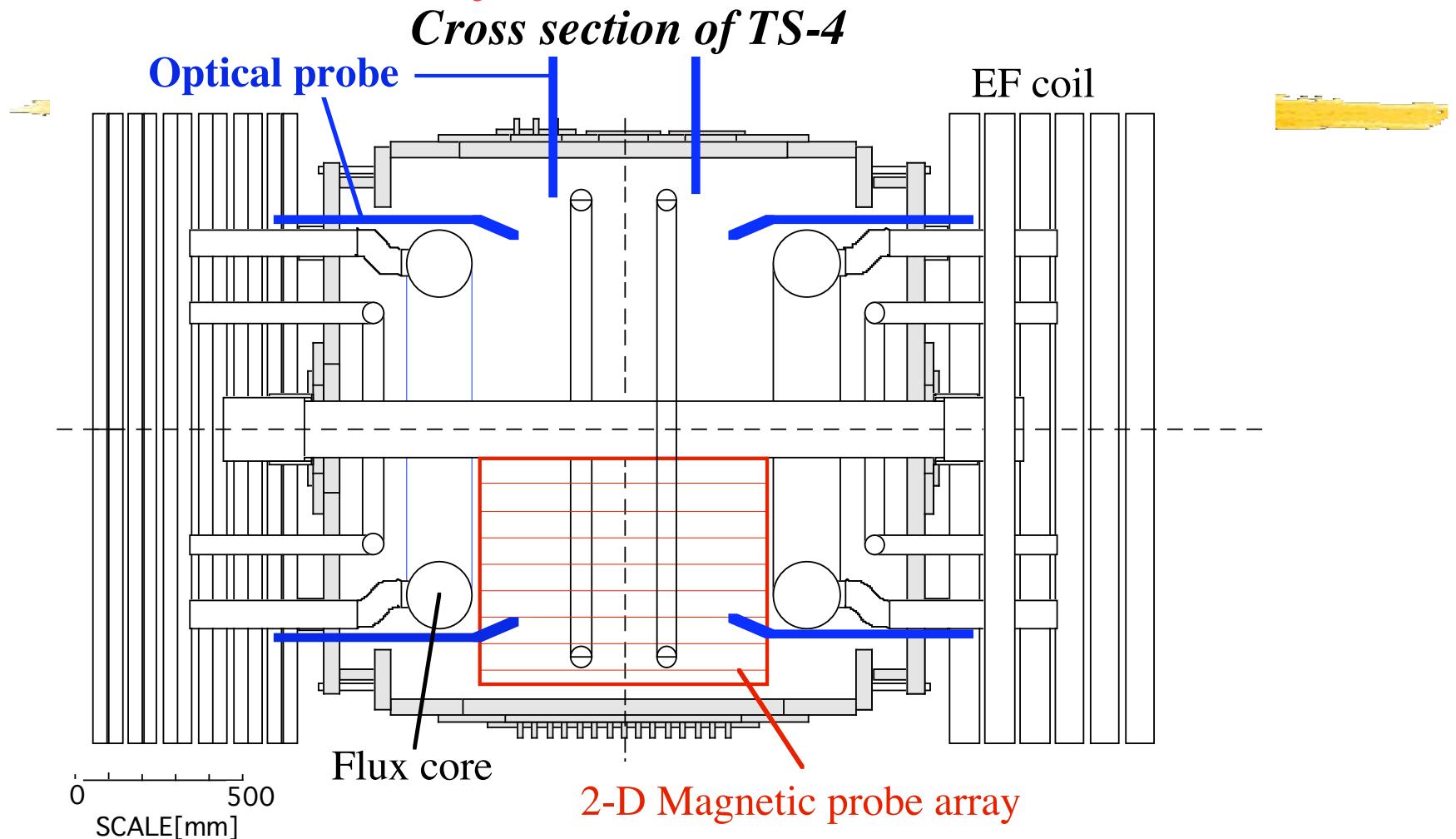
# TS-4 Merging/CT Device



- Utilizes fluxcores with PF and TF coils for poloidal and toroidal flux injection.
- All type of CTs ( $q_o \sim 0.7-5$ ) can be produced in a single device.
- $R=0.4\text{--}0.6\text{ m}$ ,  $R/a \sim 1.5$ ,  $B_{t0} \sim 0.05\text{ T}$ .



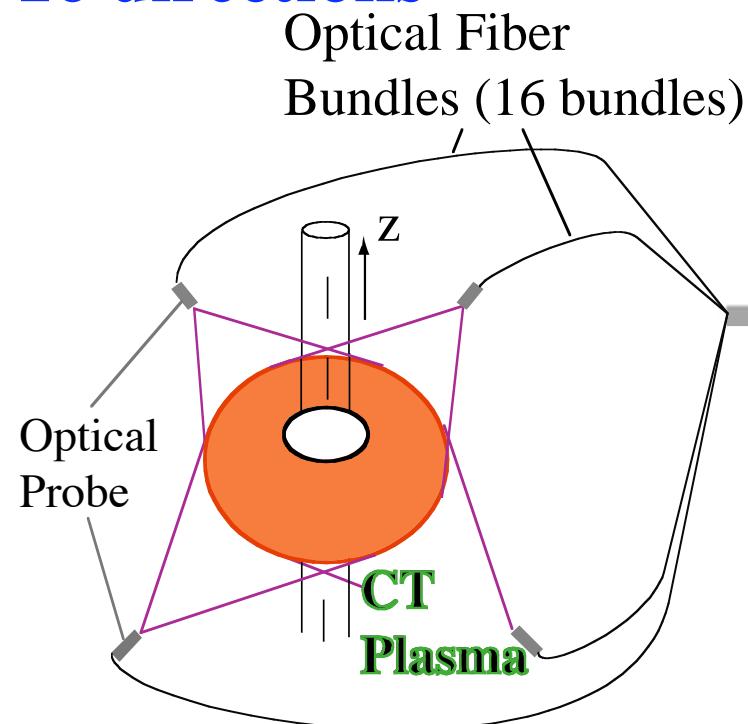
# *Measurement Systems in TS-4*



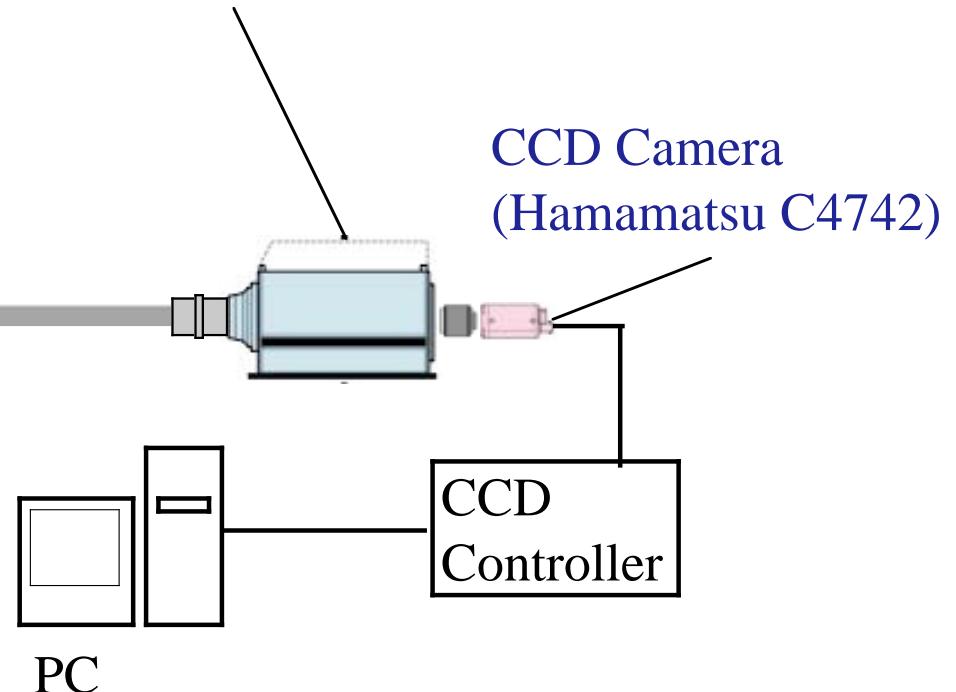
- A 2-D array of magnetic probe for calculation of flux contour
- Another 8 magnetic probes to measure toroidal modes ( $n=1 \sim 4$ )

# 3-D Tomography System

16 directions

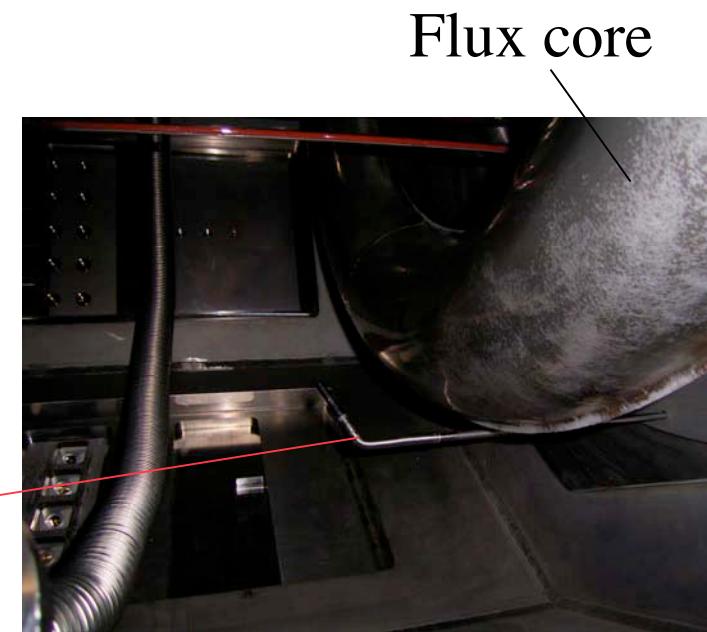
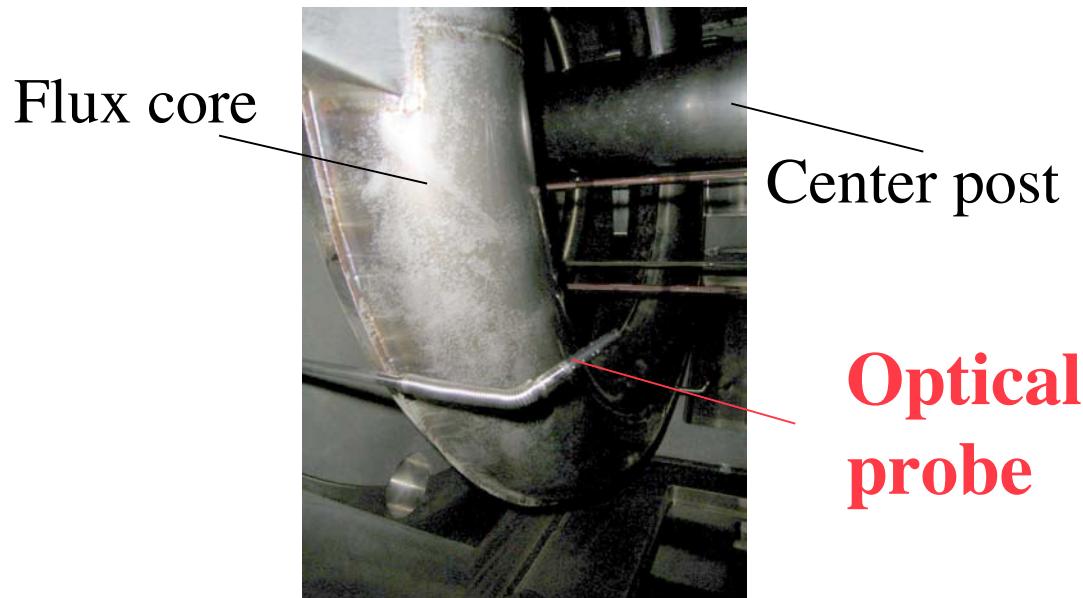
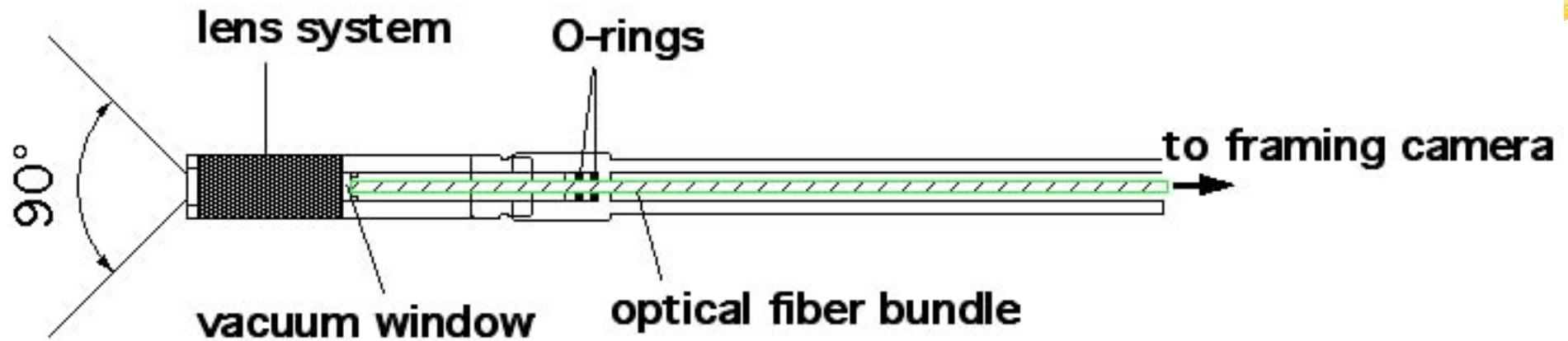


Framing-Streak Camera  
(Hamamatsu C4187)

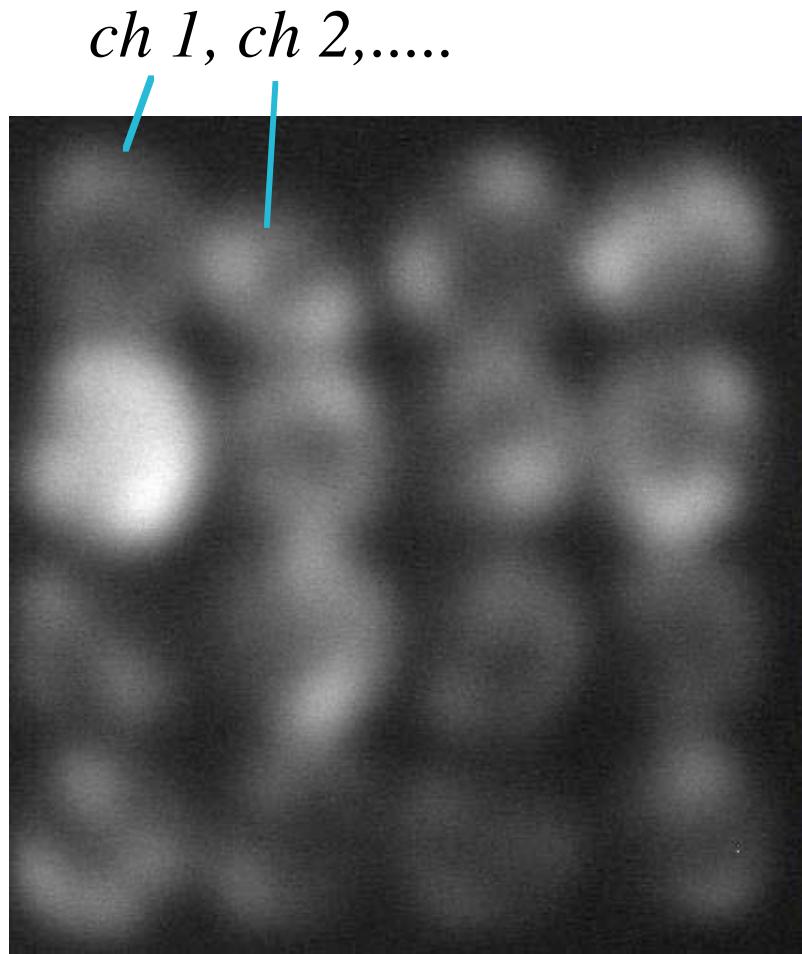


Schematic drawing of the 3-D tomography system

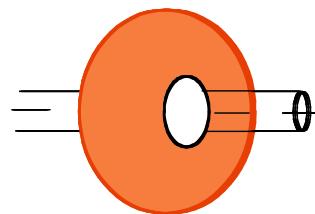
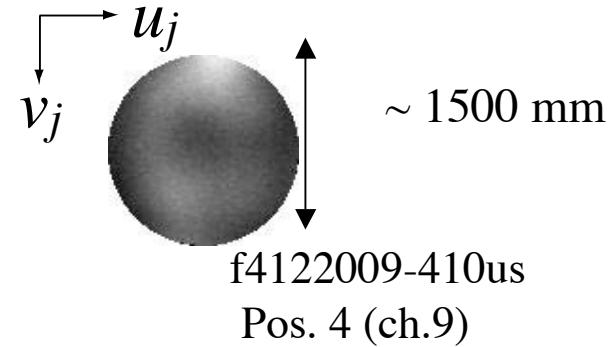
# Optical probe



# Data of the 16 projections



*Example*

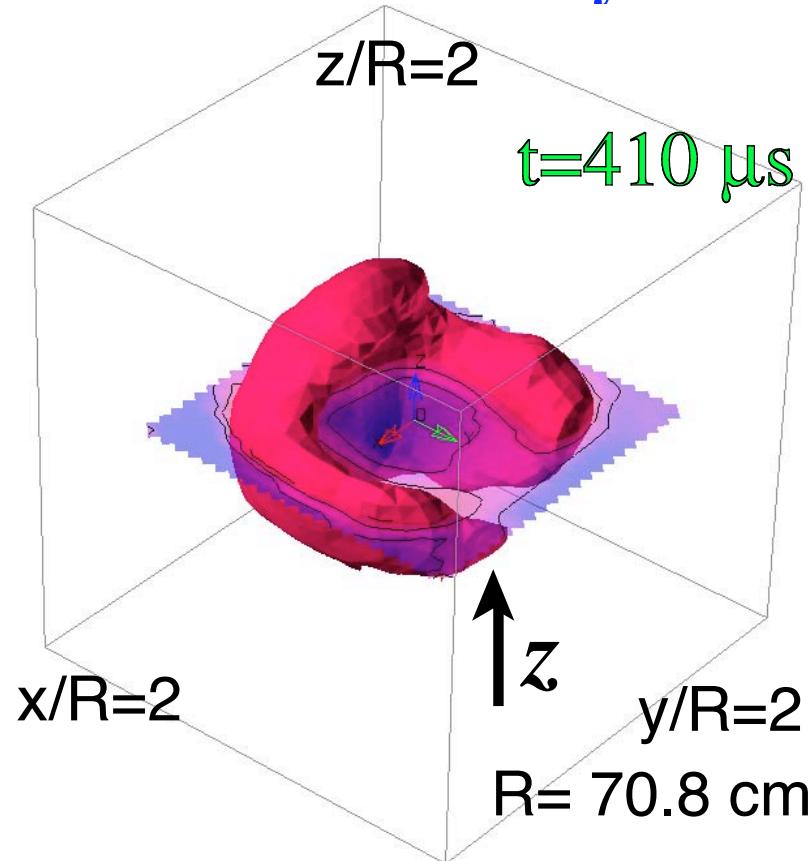


Shadow effect  
of the center  
post was seen.

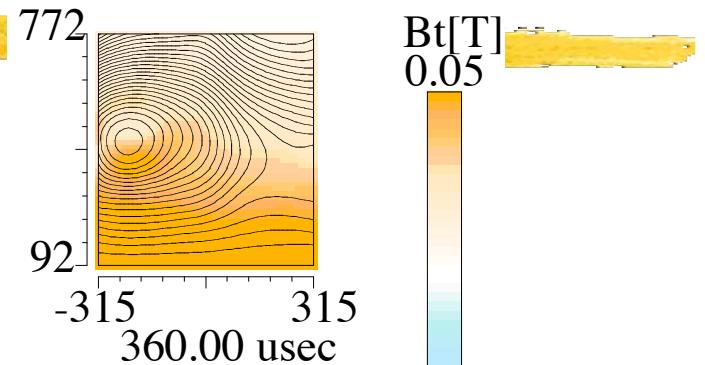
# *Reconstruction of emissivity in ST*

Data Set Name : f4113024

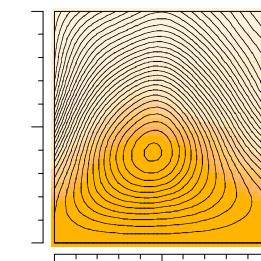
**Isosurface of the emissivity**



- Torus shape was observed however partially broken.

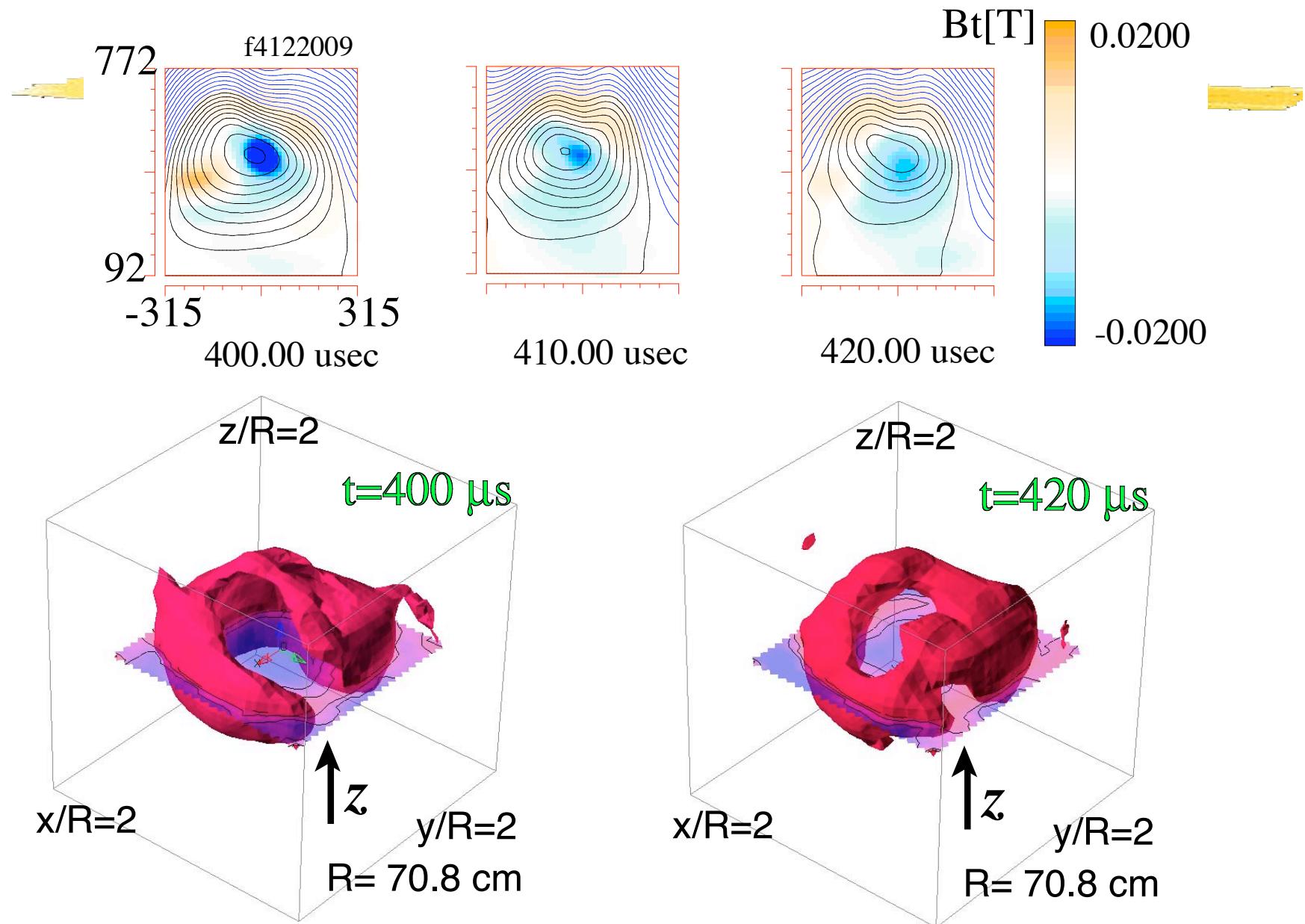


410.00 usec

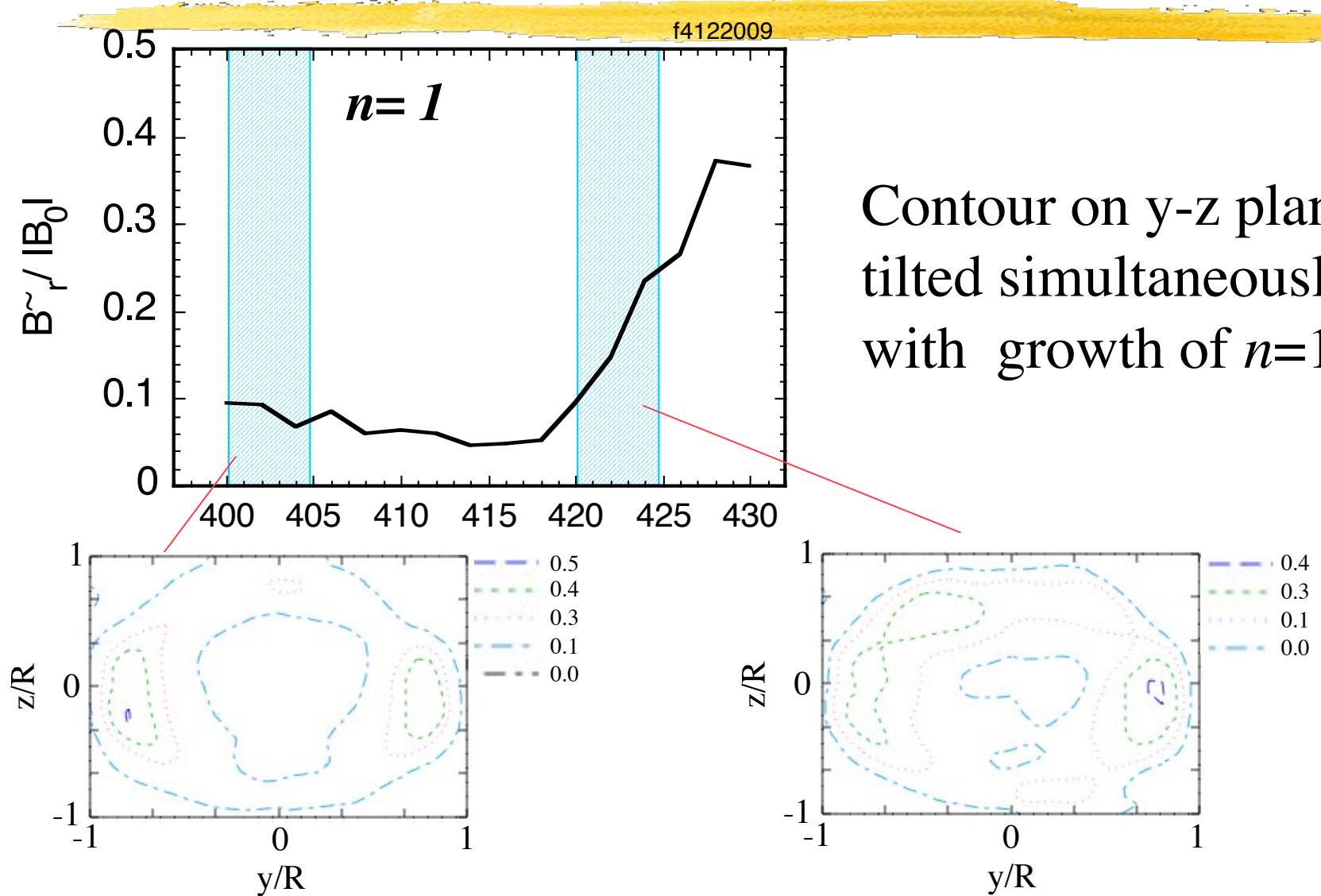


460.00 usec

# *Observed an oblate FRC tilted*



## *Tilt mode ( $n=1$ ) was observed by tomography*



## *Summary*

- The new 3-D tomography reconstruction was first experimentally tested for a powerful monitor of CT configuration using a 16-projection system of visible light tomography.
- The  $n=1$  tilt motion of FRC and the stable ST were measured successfully using the 16-projections of plasma light emissivity .
- Comparison with magnetic measurements suggests that the reconstruction error caused by edge plasma light are left unsolved.